

Hindley-Milner elaboration in applicative style

François Pottier



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a (shamefully) simple *solution*

to a *problem* that has (gently) troubled me for ten years
and whose *story* begins even longer ago.

Part I

A STORY

The 1970s



The 1970s



A Theory of Type Polymorphism in Programming

ROBIN MILNER

Computer Science Department, University of Edinburgh, Edinburgh, Scotland

Received October 10, 1977; revised April 19, 1978

Milner (1978) invents ML *polymorphism* and *type inference*.

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let $(R, \bar{d}_\rho) = \mathcal{W}(\bar{p}, d)$, and $(S, \bar{e}_\sigma) = \mathcal{W}(R\bar{p}, e)$;
let $U = \mathcal{U}(S\rho, \sigma \rightarrow \beta)$, β new;
then $T = USR$, and $\bar{f} = U(((S\bar{d})\bar{e})_0)$.

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(ii) If f is (de) then:

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UNIFY $(\rho, \sigma \rightarrow \beta)$; (β new)
 $\tau := \beta$

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Both compose *substitutions* produced by *unification*, and create “*new*” variables as needed.

The 1980s



The 1980s



A Simple Algorithm and Proof for Type Inference

Mitchell Wand*

College of Computer Science
Northeastern University

Cardelli, Wand (1987) and others formulate type inference as a two-stage process: *generating* and *solving* a conjunction of equations.

Case 3. $(A, (\lambda x.M), t)$. Let τ_1 and τ_2 be fresh type variables. Generate the equation $t = \tau_1 \rightarrow \tau_2$ and the subgoal $((A[x \leftarrow \tau_1])_M, M, \tau_2)$.

Benefits

Higher-level thinking:

instead of *substitutions* and *composition*,
equations and *conjunction*.

Greater modularity:

constraints and constraint solving as a *library*,
constraint generation performed by the *user*.

Limitations

New variables still created via a *global side effect*.

Polymorphic type inference *not supported*.

Algorithm J must *solve* the constraints produced so far (it looks up E) before it can *produce* more constraints.

The 1990s



The 1990s



$$\frac{\alpha \doteq e \wedge \alpha \doteq e'}{\alpha \doteq e \doteq e'} \text{ (FUSE)}$$
$$\frac{f(\tau_1, \dots, \tau_p) \doteq f(\beta_1, \dots, \beta_p) \doteq e}{\tau_1 \doteq \beta_1 \wedge \dots \wedge \tau_p \doteq \beta_p \wedge f(\beta_1, \dots, \beta_p) \doteq e}$$

if $f \neq g$,

$$\frac{f(\tau_1, \dots, \tau_p) \doteq g(\sigma_1, \dots, \sigma_q) \doteq e}{\perp} \text{ (FAIL)}$$

if $\alpha \in \mathcal{V}(e) \setminus e \setminus \mathcal{V}(\tau) \wedge \tau \notin \mathcal{V}$,

$$\frac{(\alpha \mapsto \tau)(e)}{\exists \alpha. (e \wedge \alpha \doteq \tau)} \text{ (GENERALIZE)}$$

Kirchner & Jouannaud (1990), Rémy (1992) and others explain “new” variables as *existential quantification* and constraint solving as *rewriting*.

A necessary step on the road towards explaining *polymorphic* inference.

The 2000s



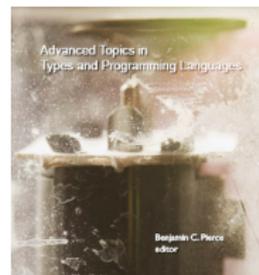
The 2000s



Constraint Abstractions

Jörgen Gustavsson and Josef Svenningsson

Chalmers University of Technology and Göteborg University
{gustavss,josefs}@cs.chalmers.se



Following Gustavsson and Svenningsson (2001), Didier Rémy and F.P. (2005) explain polymorphic type inference using *constraint abstractions*.

Constraints

Constraints offer a syntax for describing type inference problems.

$$\begin{aligned} \tau &::= \alpha \mid \tau \rightarrow \tau \mid \dots \\ C &::= \text{false} \mid \text{true} \mid C \wedge C \mid \tau = \tau \mid \exists \alpha. C \quad (\text{unification}) \\ &\quad \mid \text{let } x = \lambda \alpha. C \text{ in } C \quad (\text{abstraction}) \\ &\quad \mid x \tau \quad (\text{application}) \end{aligned}$$

The meaning of let-constraints is given by the law:

$$\begin{aligned} &\text{let } x = \lambda \alpha. C_1 \text{ in } C_2 \\ \equiv &\exists \alpha. C_1 \wedge [\lambda \alpha. C_1 / x] C_2 \end{aligned}$$

Constraint generation

A *pure function* of a term t and a type τ to a constraint $\llbracket t : \tau \rrbracket$.

$$\llbracket x : \tau \rrbracket = x \tau$$

$$\llbracket \lambda x. u : \tau \rrbracket = \exists \alpha_1 \alpha_2. \left(\begin{array}{l} \tau = \alpha_1 \rightarrow \alpha_2 \wedge \\ \text{let } x = \lambda \alpha. (\alpha = \alpha_1) \text{ in } \llbracket u : \alpha_2 \rrbracket \end{array} \right)$$

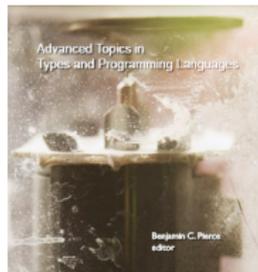
$$\llbracket t_1 t_2 : \tau \rrbracket = \exists \alpha. (\llbracket t_1 : \alpha \rightarrow \tau \rrbracket \wedge \llbracket t_2 : \alpha \rrbracket)$$

$$\llbracket \text{let } x = t_1 \text{ in } t_2 : \tau \rrbracket = \text{let } x = \lambda \alpha. \llbracket t_1 : \alpha \rrbracket \text{ in } \llbracket t_2 : \tau \rrbracket$$

Constraint solving

On paper, every constraint can be *rewritten* step by step to either false or a solved form.

The imperative implementation, based on Huet's unification algorithm and Rémy's ranks, is *efficient* (McAllester, 2003).



Library (OCaml)

Abstract syntax for constraints:

```
type variable
val fresh: variable structure option -> variable
type rawco =
| CTrue
| CConj   of rawco * rawco
| CEq     of variable * variable
| CExist  of variable * rawco
| ...
```

Combinators that build constraints:

```
val truth: rawco
val (^&) : rawco -> rawco -> rawco
val (--): variable -> variable -> rawco
val exist: (variable -> rawco) -> rawco
...

```

User (OCaml)

The user defines constraint generation:

```
let rec hastype (t : ML.term) (w : variable) : rawco
= match t with
| ...
| ML.Abs (x, u) ->
    exist (fun v1 ->
        exist (fun v2 ->
            w --- arrow v1 v2 ^&
            def x v1 (hastype u v2)
        )
    )
| ...

let iswelltyped (t : ML.term) : rawco
= exist (fun w -> hastype t w)
```

Part II

A PROBLEM

A problem

Submitting a *closed* ML term
to the generator ...

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let b = if x = y then  
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$$\exists \alpha. (\alpha = \text{bool} \wedge \exists \beta \gamma. (...))$$

either *false*, or *true*.

A problem (OCaml)

The API offered by the library is *too simple*:

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val solve :          rawco -> bool
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(Ignoring type error diagnostics.) The user has defined:

```
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```

There is no way of obtaining, say:

```
val elaborate:    ML.term -> F.term
```

which would be the front-end of a *type-directed* compiler.

Question

Can one perform *elaboration*
without compromising the *modularity* and *elegance*
of the constraint-based approach?

Part III

A SOLUTION

A low-level solution

The generator could produce a pair of

a *constraint* and

a *template for an elaborated term*,

sharing mutable placeholders for evidence,

so that, after the constraint is *solved*,

the template can be *“solidified”* into an elaborated term.

Library, low-level (OCaml)

Constraints already contain mutable placeholders for evidence:

```
... | CExist of variable * rawco | ...
```

More placeholders (not shown) required to deal with polymorphism.

Let the library offer a type decoder, which can be invoked *after* solving:

```
type decoder = variable -> ty
val new_decoder: unit -> decoder
...
```

User (OCaml)

The user could write:

```
val hastype :  
  ML.term -> variable -> rawco * F.template  
val solidify :  
  F.template -> F.term
```

where:

the constraint and the template *share* variables,
solidify uses a type decoder to replace these variables with types.

Why I not am happy with stopping here

This approach is in three stages: generation, solving, solidification.
Each user construct is dealt with *twice*, in stages 1 and 3.

This approach *exposes evidence* to the user.

Evidence is mutable and involves names and binders.

One needs an intermediate representation `F.template`,
or one must pollute `F.term`.

A wish

Even though stages 1 and 3 must be *executed* separately, the user would prefer to *describe* them in a unified manner.

A dream

If the user could somehow (magically?)

construct the constraint, and “simultaneously”

query the solver for the *final* (decoded) witness for a variable

then she would be able to perform elaboration in one swoop:

```
val elaborate: ML.term -> F.term
```

and evidence would not need to be exposed.

The idea

Give the user the *illusion* that she can use the solver in this manner.

Give her a DSL to express *computations* that:

- emit constraints *and*

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Give the user the *illusion* that she can use the solver in this manner.

Give her a DSL to express *computations* that:

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- read their solutions.

It turns out that this DSL is just

- our good old *constraints*,
- extended with a *map* combinator.

Library, high-level (OCaml)

Solving/evaluating a constraint *produces a result*.

```
type 'a co
val solve: 'a co -> 'a

val pure: 'a -> 'a co
val (^&): 'a co -> 'b co -> ('a * 'b) co
val map: ('a -> 'b) -> 'a co -> 'b co

val (--): variable -> variable -> unit co
val exist: (variable -> 'a co) -> (ty * 'a) co
...
```

E.g., evaluating $\exists\alpha.C$ yields a *pair* of a decoded type (the *witness* for α) and the value of C .

Library, high-level (OCaml)

This is implemented *on top of* the earlier, low-level library.

```
type env =  
  decoder  
type 'a co =  
  rawco * (env -> 'a)
```

A constraint/computation is a pair of

- ▶ a raw *constraint*, which contains mutable evidence;
- ▶ a *continuation*, which reads this evidence *after* the solver has run.

Library, high-level (OCaml)

The implementation is quasi-trivial.

```
let exist f =  
  let v = fresh None in  
  let rc, k = f v in  
  CExist (v, rc),  
  fun env ->  
    let decode = env in  
    (decode v, k env)
```

User (OCaml)

The user defines inference/elaboration in *one* inductive function:

```
let rec hastype t w : F.term co
= match t with
| ...
| ML.Abs (x, u) ->
  exist (fun v1 ->
    exist (fun v2 ->
      w --- arrow v1 v2 ^&
      def x v1 (hastype u v2)
    )
  ) <$$> fun (ty1, (ty2, ((), u'))) ->
  F.Abs (x, ty1, u')
| ...
```

The (final, decoded) type ty1 of x seems to be *magically* available.

Remarks

Elaboration from ML to System F in the paper (and online).

The type `'a co` forms an *applicative functor*, not a monad.

Part IV

Conclusion

Conclusion

- ▶ a simple idea, really
- ▶ just icing on the cake
- ▶ modularity, elegance, performance
- ▶ usable in other settings? e.g. higher-order pattern unification?

Thank you

`http://gallium.inria.fr/~fpottier/inferno/`

No mutable state was exposed in the making of this library.